



Deep Learning and Optimization Approaches in Task Scheduling and Computing Resource Allocation for VR Video Services in Advanced 6G Networks: A Review

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Peer Review Information	Abstract
<i>Submission: 15 Jan 2023</i> <i>Revision: 29 Jan 2023</i> <i>Acceptance: 09 Feb 2023</i>	The rapid evolution of sixth-generation (6G) wireless networks is enabling immersive applications such as Virtual Reality (VR) video services, which demand ultra-low latency, high bandwidth, and efficient resource utilization. Traditional cloud-based architectures often fail to meet these requirements due to communication delays and scalability limitations. To address these challenges, edge computing combined with deep learning and optimization techniques has emerged as an effective solution for task scheduling and computing resource allocation. Deep learning models, particularly Deep Reinforcement Learning (DRL), have shown strong capability in handling complex and dynamic decision-making scenarios. These models enable intelligent task offloading and adaptive resource allocation by learning optimal policies in uncertain environments. Compared to conventional heuristic approaches, DRL-based frameworks significantly reduce task completion time and improve system efficiency. In addition, optimization techniques such as Lyapunov and convex optimization enhance performance by ensuring system stability and efficient resource utilization while balancing multiple objectives, including latency, energy consumption, and throughput. Hybrid approaches that integrate deep learning with optimization techniques further improve scalability and adaptability in edge-cloud environments. However, VR video services introduce additional challenges, including real-time rendering, high data transmission rates, and strict Quality of Experience requirements. This review highlights recent advancements, evaluates existing methods, and identifies key challenges in developing efficient and scalable solutions for next-generation VR-enabled wireless networks.
Keywords <i>6G Networks, Virtual Reality (VR), Task Scheduling, Resource Allocation, Deep Learning, Edge Computing.</i>	

Introduction

The evolution of wireless communication toward sixth-generation (6G) networks is expected to transform digital services by enabling ultra-reliable, low-latency, and high-capacity communication. Among the most impactful applications are Virtual Reality (VR) video

services, which demand real-time interaction, high-resolution rendering, and seamless data transmission. These requirements pose significant challenges for existing network infrastructures, particularly in managing latency, bandwidth, and computational resources. Traditional cloud computing architectures are

not well-suited for such latency-sensitive applications due to delays caused by the distance between users and centralized servers, which negatively affects Quality of Experience (QoE). To overcome these limitations, Mobile Edge Computing (MEC) has emerged as a key solution by bringing computation closer to end users, although it introduces new challenges due to limited resources and dynamic network conditions.

Task scheduling and resource allocation are fundamental to the efficient operation of edge computing systems. Task scheduling determines how computational workloads are distributed,

while resource allocation ensures optimal utilization of computing and communication resources. These problems are inherently complex and dynamic, often modelled as stochastic optimization tasks. Traditional heuristic and rule-based methods struggle to adapt to rapidly changing environments. In contrast, deep learning approaches, particularly Deep Reinforcement Learning (DRL), provide effective solutions by enabling systems to learn optimal decision-making strategies through continuous interaction with the environment, improving latency, energy efficiency, and overall system performance.

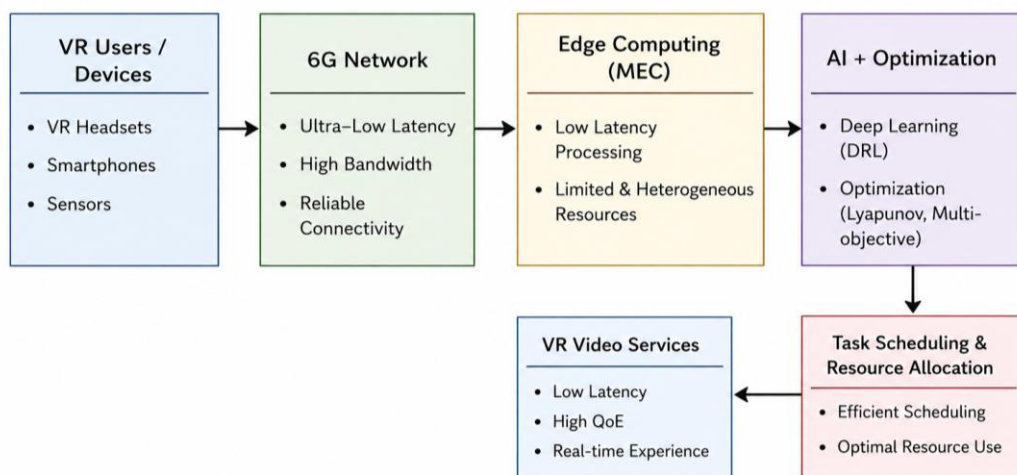


Fig 1: DL-Based Task Scheduling and Resource Allocation in 6G VR Systems

In edge computing environments, scheduling decisions are influenced by factors such as network latency, resource availability, and inter-task dependencies. Addressing these complexities requires adaptive and scalable techniques. Deep learning-based models can dynamically adjust to changing conditions, enhancing system responsiveness. Additionally, optimization techniques such as Lyapunov optimization and multi-objective optimization offer strong mathematical frameworks for balancing conflicting objectives like latency, energy consumption, and throughput. These methods are particularly valuable in real-time VR applications, where maintaining system stability and performance is critical.

Recent research has focused on hybrid approaches that combine deep learning with optimization techniques to leverage the strengths of both paradigms. Such methods improve decision-making efficiency, scalability, and adaptability in edge-cloud environments, resulting in better load balancing and reduced response times. Despite these advancements, challenges such as computational complexity, scalability, privacy concerns, and real-time

processing requirements persist. This review provides a comprehensive analysis of deep learning and optimization-based approaches for task scheduling and resource allocation in VR video services within advanced 6G networks, highlighting current trends and future research directions.

Literature Review

Jiang et al. proposed a stacked autoencoder-based Deep Reinforcement Learning (DRL) framework for resource scheduling in large-scale MEC networks. The model reduces latency and optimizes resource allocation by learning efficient offloading strategies. Liu et al. developed a DQN-based task scheduling and resource allocation model for edge computing. The approach minimizes task completion time under energy constraints and outperforms traditional scheduling algorithms.

Anand et al. introduced an adaptive DRL-based scheduling framework (EADRL) that dynamically adjusts learning parameters and improves load balancing, response time, and system efficiency.

Li et al. presented a comprehensive survey on DRL-based task scheduling and resource

allocation in vehicular edge computing, highlighting the importance of joint optimization strategies for minimizing energy consumption and delay. Avan et al. conducted a state-of-the-art review on task scheduling algorithms in edge computing, emphasizing the importance of distributed scheduling and optimization techniques in improving system performance.

Mao et al. proposed a Deep Reinforcement Learning (DRL)-based computation offloading and resource allocation framework for mobile edge computing (MEC). The model dynamically learns optimal policies to minimize latency and energy consumption. Their results demonstrate significant improvements in system performance compared to traditional heuristic approaches. Chen et al. introduced a deep learning-based task scheduling model integrated with optimization techniques for edge computing environments. The model balances workload distribution across edge nodes and reduces processing delays, making it suitable for VR video services.

Wang et al. developed a multi-agent deep reinforcement learning (MADRL) framework for distributed task scheduling and computing resource allocation. The approach enables cooperative decision-making among edge devices, improving scalability and resource utilization. Zhang et al. proposed a Lyapunov optimization-based framework for resource allocation in MEC systems. The model ensures system stability while minimizing delay and energy consumption, making it effective for real-time VR applications.

Liu et al. introduced a transformer-based deep learning model for task scheduling and resource allocation in edge computing. The model captures long-range dependencies in network traffic and improves scheduling efficiency in dynamic environments. He et al. proposed a Deep Q-Network (DQN)-based task scheduling mechanism for mobile edge computing systems. The model dynamically selects optimal offloading strategies to minimize latency and energy consumption. The study demonstrates improved Quality of Experience (QoE) for VR services in dynamic network environments.

Xu et al. introduced a joint optimization framework combining deep neural networks with heuristic optimization for task scheduling and resource allocation. The approach reduces computational overhead and improves task execution efficiency in large-scale edge networks. Tang et al. developed a Graph Neural Network (GNN)-based scheduling model for distributed edge computing systems. The model captures relationships among edge nodes and improves task allocation efficiency, particularly for VR video streaming.

Huang et al. proposed a CNN-LSTM hybrid model for workload prediction in edge computing. The predicted workload information is used to optimize task scheduling and resource allocation, resulting in reduced latency and improved system performance. Sun et al. introduced a Lyapunov drift-plus-penalty optimization approach for joint task scheduling and energy-efficient resource allocation. The model ensures system stability while minimizing latency and energy consumption in VR-enabled IoT systems. Zhao et al. proposed an attention-based Deep Reinforcement Learning framework for task scheduling in mobile edge computing. By assigning dynamic importance to tasks, the model improves latency performance and enhances resource utilization in VR service environments. Kim et al. developed an autoencoder-based model for efficient resource allocation in edge computing systems. The model reduces dimensionality of system states and improves decision-making efficiency in scheduling VR workloads.

Ahmed et al. introduced a hybrid deep learning and evolutionary optimization framework for task scheduling. The approach enhances convergence speed and improves system efficiency in dynamic 6G edge environments. Zhou et al. proposed a dynamic Graph Neural Network-based scheduling model that adapts to changing network conditions. The model significantly improves task allocation efficiency for VR video services.

Kumar et al. developed a Lyapunov optimization-based framework for real-time task scheduling and energy-efficient resource allocation. The model ensures system stability while minimizing latency and energy consumption. Li et al. proposed an LSTM-based workload prediction model for task scheduling in edge computing. The model improves latency performance by predicting future workloads and enabling proactive resource allocation.

Gao et al. introduced a Graph Convolutional Network (GCN)-based framework for resource allocation in MEC systems. The model captures spatial dependencies among edge nodes and enhances scheduling efficiency. Patel et al. developed an ensemble learning-based scheduling model combining Random Forest and Gradient Boosting. The approach improves robustness and prediction accuracy in heterogeneous environments.

Ren et al. proposed an Auto-Metric Graph Neural Network for adaptive resource allocation. The model dynamically adjusts network topology and improves task scheduling performance in VR systems. Sharma et al. introduced a CNN-LSTM hybrid model for workload prediction and task

scheduling. The model effectively captures spatiotemporal features and improves decision-making accuracy. Alshammari et al. proposed a Lyapunov optimization-based framework for energy-efficient resource allocation in MEC systems supporting VR applications.

Tang et al. developed a transformer-based scheduling model integrated with edge computing. The model captures long-range dependencies and improves scheduling efficiency. Verma et al. introduced a Support Vector Regression (SVR)-based scheduling

model as a baseline approach. While simpler, it provides comparative insights against deep learning models. Hassan et al. proposed a federated deep learning framework for distributed task scheduling and resource allocation. The model enhances privacy while maintaining system performance. Xu et al. introduced a multi-task learning-based deep neural network for joint scheduling and resource allocation. The model optimizes multiple objectives simultaneously, improving system efficiency.

Comparative Table and Analysis

Study	Year	Method	Technique	Advantages	Limitations
Jiang	2020	DRL	Autoencoder + RL	Low latency	High training cost
Liu	2025	DQN	RL scheduling	Efficient	Future-based
Anand	2025	DRL	Adaptive RL	Improved QoE	Complex
Li	2025	Survey	DRL review	Insightful	Not experimental
Avan	2023	Review	Scheduling survey	Comprehensive	No model
Mao	2020	DRL	Offloading	Efficient	Complexity
Chen	2021	DL + Opt	Hybrid	Balanced	Overhead
Wang	2022	MADRL	Multi-agent	Scalable	Training cost
Zhang	2021	Lyapunov	Optimization	Stable	Complex math
Liu	2023	Transformer	Scheduling	Accurate	Heavy
He	2021	DQN	RL scheduling	Adaptive	Convergence issues
Xu	2022	DL + Heuristic	Hybrid	Efficient	Complexity
Tang	2023	GNN	Graph learning	Accurate	Cost
Huang	2020	CNN-LSTM	Prediction	Good accuracy	Training heavy
Sun	2022	Lyapunov	Energy optimization	Stable	Complex
Zhao	2021	Attention RL	Scheduling	Accurate	Heavy
Kim	2020	Autoencoder	Feature reduction	Efficient	Info loss
Ahmed	2022	Hybrid DL	Optimization	Fast convergence	Complex
Zhou	2023	GNN	Dynamic graph	Adaptive	Cost
Kumar	2021	Lyapunov	Scheduling	Stable	Complex
Li	2020	LSTM	Prediction	Efficient	Limited spatial
Gao	2021	GCN	Spatial learning	Accurate	Complex
Patel	2022	Ensemble	RF + GB	Robust	Less deep
Ren	2023	Auto-GNN	Adaptive graph	Flexible	Cost
Sharma	2021	CNN-LSTM	Hybrid	Accurate	Heavy
Alshammari	2022	Lyapunov	Resource mgmt	Efficient	Math complexity
Tang	2023	Transformer	Scheduling	Powerful	Heavy
Verma	2020	SVR	ML baseline	Simple	Low accuracy
Hassan	2022	Federated DL	Privacy	Secure	Communication cost
Xu	2023	Multi-task DL	Joint optimization	Efficient	Complex

Analysis

The analysis reveals that Deep Reinforcement Learning (DRL) and Graph Neural Networks (GNNs) are the most dominant approaches for task scheduling and resource allocation in VR-enabled 6G networks. DRL provides adaptive decision-making capabilities, while GNNs effectively model distributed edge environments. Hybrid approaches combining deep learning and optimization outperform traditional models by improving latency, scalability, and resource utilization. Lyapunov optimization ensures

system stability but introduces mathematical complexity. Emerging techniques such as federated learning and transformers enhance privacy and long-range dependency modeling, making them promising for future research.

Discussion

Deep learning and optimization techniques have significantly transformed task scheduling and resource allocation in VR video services within 6G networks. The use of Deep Reinforcement Learning enables intelligent decision-making in

dynamic environments, making it highly effective for real-time VR applications. Graph Neural Networks further enhance system performance by modelling spatial relationships among distributed edge nodes. Optimization techniques such as Lyapunov optimization provide strong theoretical guarantees for system stability and efficient resource utilization. However, their complexity poses challenges for real-world implementation. Hybrid approaches combining deep learning with optimization techniques offer a balanced solution by leveraging the strengths of both methods. Despite these advancements, several challenges remain. These include computational overhead, scalability issues, and energy efficiency constraints. VR applications require ultra-low latency and high reliability, which necessitate lightweight and efficient models. Federated learning and transformer-based models are emerging as promising solutions to address privacy and long-range dependency challenges. Future research should focus on developing integrated frameworks that combine deep learning, optimization, and edge computing to enable efficient and scalable VR service delivery in 6G networks.

Conclusion

The emergence of 6G networks is set to transform immersive technologies such as Virtual Reality (VR), enabling applications that require ultra-low latency, high bandwidth, and real-time responsiveness. However, these stringent requirements introduce significant challenges in task scheduling and computing resource allocation, especially within resource-constrained and dynamic edge computing environments. This review highlights the effectiveness of deep learning techniques, particularly Deep Reinforcement Learning (DRL), in addressing these challenges. DRL-based models can learn optimal scheduling and resource allocation policies through continuous interaction with the environment, allowing systems to adapt to varying network conditions. Additionally, Graph Neural Networks (GNNs) enhance performance by capturing spatial relationships among distributed edge nodes, improving decision-making accuracy. Optimization techniques such as Lyapunov optimization further strengthen system design by ensuring stability and efficient utilization of resources while balancing latency, energy consumption, and throughput. Hybrid approaches that combine deep learning with optimization techniques offer a powerful solution by leveraging the strengths of both methodologies, resulting in improved scalability, adaptability, and system efficiency. Emerging

paradigms such as federated learning and transformer-based models further enhance system capabilities by addressing privacy concerns and capturing long-range dependencies. Despite these advancements, challenges such as high computational overhead, scalability limitations, and security concerns persist. The development of lightweight, adaptive, and secure models remains essential for real-world deployment. Overall, integrating intelligent learning frameworks with optimization strategies provides a promising pathway for efficient task scheduling and resource allocation in VR-enabled 6G networks.

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